

Non-Linear Programming (NLP): Single-Variable, Unconstrained

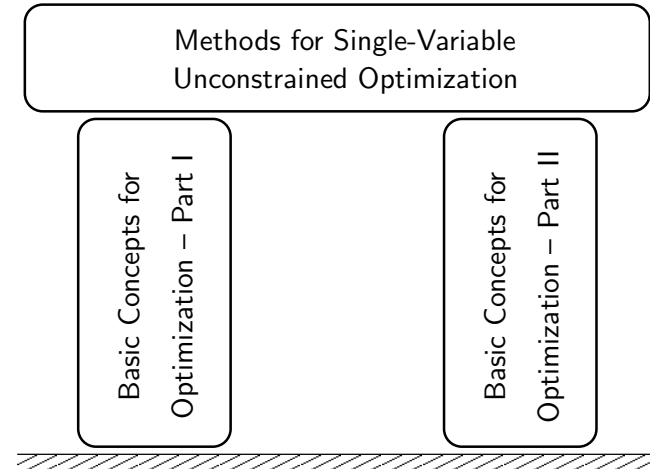
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ChE 4G03: Optimization in Chemical Engineering

Solving Single-Variable, Unconstrained NLPs

Prerequisites:



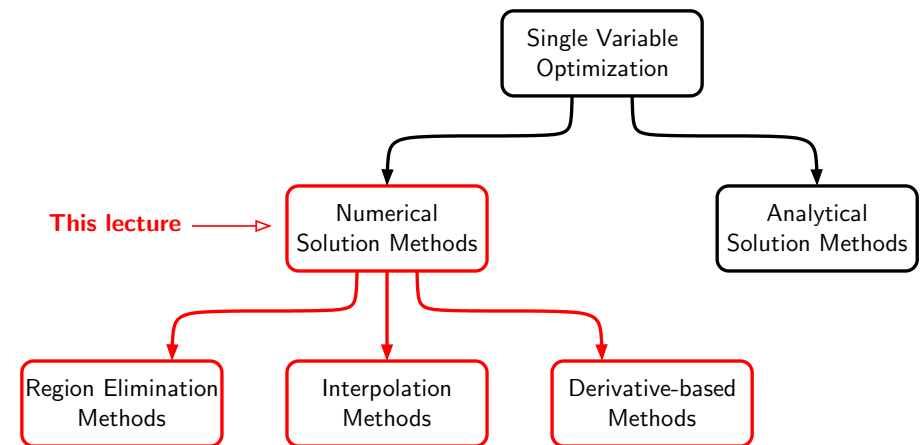
Solving Single-Variable, Unconstrained NLPs

- “Aren’t single-variable problems easy?” — **Sometimes**
- “Won’t the methods for multivariable problems work in the single variable case?” — **Yes**

But,

- 1 A few **important** problems are single variables — e.g., nonlinear regression
- 2 This will give us **insight** into multivariable solution techniques
- 3 Single-variable optimization is a **subproblem** for many nonlinear optimization methods and software! — e.g., linesearch in (un)constrained NLP

Outline

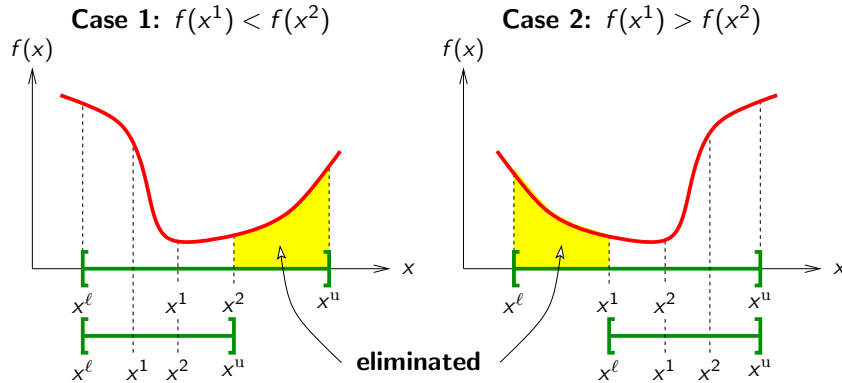


For additional details, see Rardin (1998), Chapter 13.2

Region Elimination Methods (Minimize Case)

Iteratively consider the function value at 4 carefully spaced points:

- Assume a **unimodal** function
- Leftmost x^l is **always a lower bound** on the optimal value x^*
- Rightmost x^u is **always an upper bound** on the optimal value x^*
- Points x^1 and x^2 fall in between



Golden Section Search (Minimize Case)

How do we choose the intermediate points x^1, x^2 ?

- Golden section search proceeds by keeping both possible intervals $[x^l, x^2]$ or $[x^1, x^u]$ equal

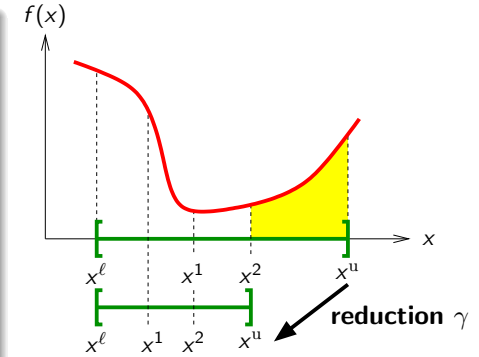
Golden Section Search

The points x^1, x^2 are taken as:

$$x^1 \triangleq x^u - \gamma [x^u - x^l]$$

$$x^2 \triangleq x^l + \gamma [x^u - x^l]$$

with $\gamma \triangleq \frac{1 + \sqrt{5}}{2} \approx 0.618$ a fraction known as the **golden ratio**



What is the advantage of choosing this ratio γ ?

Golden Section Search Algorithm (Minimize Case)

- **Step 0: Initialization**
 - ▶ Choose lower and upper bounds, x^l and x^u , that bracket x^* , as well as stopping tolerance $\epsilon > 0$
 - ▶ Set $x^1 \leftarrow x^u - \gamma [x^u - x^l]$ and $x^2 \leftarrow x^l + \gamma [x^u - x^l]$
- **Step 1: Stopping**
 - ▶ If $x^u - x^l < \epsilon$, **stop** — report $x^* \leftarrow \frac{1}{2} [x^u - x^l]$ as an approximate solution
- **Step 2a: Case $f(x^1) < f(x^2)$ (optimum left)**
 - ▶ Narrow the search by eliminating the rightmost part:

$$x^u \leftarrow x^2, \quad x^2 \leftarrow x^1, \quad x^1 \leftarrow x^u - \gamma [x^u - x^l],$$
 and evaluate $f(x^1)$ — **Return to step 1**
- **Step 2b: Case $f(x^1) > f(x^2)$ (optimum right)**
 - ▶ Narrow the search by eliminating the leftmost part:

$$x^l \leftarrow x^1, \quad x^1 \leftarrow x^2, \quad x^2 \leftarrow x^l + \gamma [x^u - x^l],$$
 and evaluate $f(x^2)$ — **Return to step 1**

Pros and Cons of Golden Section Search

Pros:

- Objective function can be **nonsmooth** or even **discontinuous**
- Calculations are **straightforward** (only function evaluations)

Cons:

- Assumes a **unimodal** function and requires prior knowledge of an **enclosure** $x^* \in [x^l, x^u]$
- Golden section search is **slow!** Considerable computation may be needed to get an accurate solution

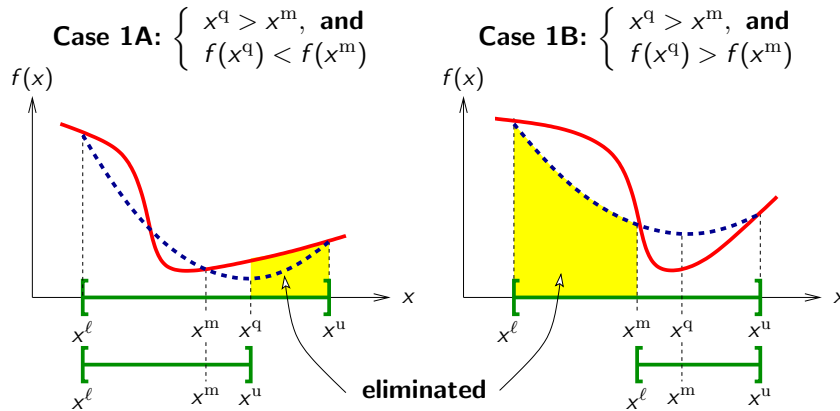
Example: Consider the problem: $\min f(x) \triangleq \frac{(x-20)^4}{500} - 2x$

it.	x^l	x^1	x^2	x^u	$f(x^l)$	$f(x^1)$	$f(x^2)$	$f(x^u)$	$x^u - x^l$
0	0.00	15.28	24.72	40.00	320.00	-29.57	-48.45	240.00	40.00
1	15.28	24.72	30.54	40.00	-29.57	-48.45	-36.27	240.00	24.72
2	15.28	21.12	24.72	30.56	-29.57	-42.23	-48.45	-36.27	15.28
3	21.12	24.72	26.95	30.56	-42.23	-48.45	-49.23	-36.27	9.44
4									

Interpolation Methods (Minimize Case)

Improve speed by taking full advantage of a 3-point pattern:

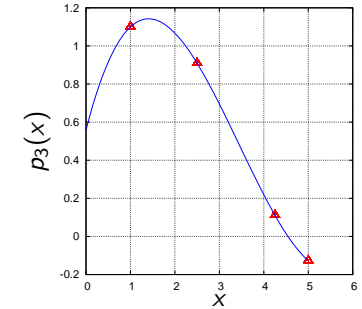
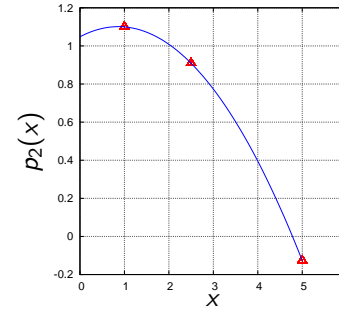
- Assume a **unimodal, continuous** function
- Fit a smooth curve through the points: $(x^\ell, f(x^\ell))$, $(x^m, f(x^m))$, $(x^u, f(x^u))$; then, optimize the fitted curve



Math Refresher: Lagrange Polynomials

- For $N + 1$ data points, there is **one and only one** polynomial of order N , $p_N(x) \triangleq a_0 + a_1x + \dots + a_Nx^N$, passing through **all** the points
- The Lagrange polynomials provide **one way** of computing this interpolation:

$$p_N(x) \triangleq \sum_{k=0}^N p(x_k) \mathcal{L}_k(x), \quad \text{with: } \mathcal{L}_k(x) \triangleq \prod_{\substack{i=1 \\ i \neq k}}^N \frac{x - x_i}{x_k - x_i}$$



Quadratic Fit Search (Minimize Case)

How do we fit the curve?

- Quadratic fit search proceeds by fitting a 2nd-order polynomial through $(x^\ell, f(x^\ell))$, $(x^m, f(x^m))$, $(x^u, f(x^u))$:

$$p_2(x) \triangleq f(x^\ell) \frac{(x - x^m)(x - x^u)}{(x^\ell - x^m)(x^\ell - x^u)} + f(x^m) \frac{(x - x^\ell)(x - x^u)}{(x^m - x^\ell)(x^m - x^u)} + f(x^u) \frac{(x - x^\ell)(x - x^m)}{(x^u - x^\ell)(x^u - x^m)}$$

Quadratic Fit Search

The **unique** optimum of the fitted quadratic function occurs at:

$$x^q \triangleq \frac{1}{2} \frac{f(x^\ell) [x^{m2} - x^{u2}] + f(x^m) [x^{u2} - x^{\ell2}] + f(x^u) [x^{\ell2} - x^{m2}]}{f(x^\ell) [x^m - x^u] + f(x^m) [x^u - x^\ell] + f(x^u) [x^\ell - x^m]}$$

Quadratic Fit Search Algorithm (Minimize Case)

- Step 0: Initialization**
 - Choose starting 3-point pattern (x^ℓ, x^m, x^u) , as well as stopping tolerance $\epsilon > 0$
- Step 1: Stopping**
 - If $x^u - x^\ell < \epsilon$, **stop** — report $x^* \leftarrow x^m$ as an approximate solution
- Step 2: Quadratic Fit**
 - Compute quadratic fit optimum x^q as

$$x^q \leftarrow \frac{1}{2} \frac{f(x^\ell) [x^{m2} - x^{u2}] + f(x^m) [x^{u2} - x^{\ell2}] + f(x^u) [x^{\ell2} - x^{m2}]}{f(x^\ell) [x^m - x^u] + f(x^m) [x^u - x^\ell] + f(x^u) [x^\ell - x^m]}$$
- Step 3a: Case $x^q < x^m$**
 - If $f(x^q) > f(x^m)$, update $x^\ell \leftarrow x^q$
 - Otherwise, update $x^u \leftarrow x^m$, $x^m \leftarrow x^q$
 - Return to step 1**
- Step 3b: Case $x^q > x^m$**
 - If $f(x^q) > f(x^m)$, update $x^h \leftarrow x^q$
 - Otherwise, update $x^\ell \leftarrow x^m$, $x^m \leftarrow x^q$
 - Return to step 1**

Pros and Cons of Quadratic Fit Search

Pros:

- Calculations are also **straightforward** (only function evaluations)
- Typically faster than Golden section search (but not so much...)

Cons:

- Assumes a **unimodal** function and requires prior knowledge of an **enclosure** $x^* \in [x^l, x^u]$
- Objective function has to be **smooth**

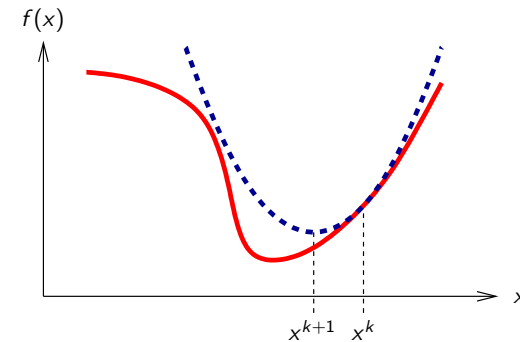
Example: Consider the problem: $\min f(x) \triangleq \frac{(x-20)^4}{500} - 2x$

it.	x^l	x^m	x^u	$f(x^l)$	$f(x^m)$	$f(x^u)$	$x^u - x^l$	x^q	$f(x^q)$
0	0.00	32.00	40.00	320.00	-22.53	240.00	40.00	20.92	-41.84
1	0.00	20.92	32.00	320.00	-41.84	-22.53	32.00	25.00	-48.75
2	20.92	25.00	32.00	-41.84	-48.75	-22.53	11.80	30.00	-40.03
3	20.92	25.00	30.00	-41.84	-48.75	-40.03	9.08		
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Derivative-Based Methods

Improve convergence speed by using first- and second-order derivatives taking full advantage of a 3-point pattern:

- Assume a **smooth** function f
- Consider the quadratic approximation of f passing through the current iterate x^k
- Optimize this approximation to determine the next iterate, x^{k+1}



Newton's Method

How do we get a quadratic approximation at x^k ?

- Use Taylor series approximation:

$$f(x) \approx f(x^k) + f'(x^k) [x - x^k] + \frac{1}{2} f''(x^k) [x - x^k]^2$$

- Calculate the optimum, x^{k+1} , of the quadratic approximation:

$$f'(x^{k+1}) = 0 = f'(x^k) + f''(x^k) [x^{k+1} - x^k]$$

Basic Newton's Search

The basic Newton's method proceeds **iteratively** as

$$x^{k+1} \triangleq x^k - \frac{f'(x^k)}{f''(x^k)}$$

The term $d^{k+1} \triangleq -\frac{f'(x^k)}{f''(x^k)}$ is called the **Newton step**.

Basic Newton Algorithm

• Step 0: Initialization

- ▶ Choose an initial guess x^0 , as well as stopping tolerance $\epsilon > 0$
- ▶ Set $k \leftarrow 0$

• Step 1: Derivatives

- ▶ Compute first- and second-order derivatives $f'(x^k)$, $f''(x^k)$

• Step 2: Stopping

- ▶ If $|f'(x^k)| < \epsilon$, **stop** — report $x^* \leftarrow x^k$ as an approximate solution

• Step 3: Newton Step

- ▶ Compute Newton step $d^{k+1} \leftarrow -\frac{f'(x^k)}{f''(x^k)}$
- ▶ Update iterate $x^{k+1} \leftarrow x^k + d^{k+1}$
- ▶ Increment $k \leftarrow k + 1$ and **return to step 1**

Variante: Quasi-Newton Algorithm

Idea: Approximate second-order derivatives using finite differences,

$$f''(x^k) \approx \frac{f'(x^k) - f'(x^{k-1})}{x^k - x^{k-1}}$$

• Step 0: Initialization

- ▶ Choose initial points x^{-1} and x^0 , as well as stopping tolerance $\epsilon > 0$
- ▶ Set $k \leftarrow 0$

• Step 1: Derivatives

- ▶ Compute first-order derivative $f'(x^k)$ and approximate inverse of second-order derivatives $B(x^k) \triangleq \frac{x^k - x^{k-1}}{f'(x^k) - f'(x^{k-1})}$

• Step 2: Stopping

- ▶ If $|f'(x^k)| < \epsilon$, **stop** — report $x^* \leftarrow x^k$ as an approximate solution

• Step 3: Newton Step

- ▶ Compute Newton step $d^{k+1} \leftarrow -f'(x^k)B^k$
- ▶ Update iterate $x^{k+1} \leftarrow x^k + d^{k+1}$
- ▶ Increment $k \leftarrow k + 1$ and **return to step 1**

Pros and Cons of (Quasi-)Newton Search

Pros:

- Very **fast convergence** close to the optimal solution (quadratic convergence rate)
- No need to bound the optimum within a range

Cons:

- Requires a “good” **initial guess**, otherwise typically diverges
- No distinction between (local) **minima and maxima!**
- Objective function has to be **smooth** and first-order derivatives must be available (possibly second-order derivatives too)

Example: Consider the problem: $\min f(x) \triangleq \frac{(x-20)^4}{500} - 2x$

k	x^k	$f(x^k)$	$f'(x^k)$	$f''(x^k)$	$ f'(x^k) $	d^{k+1}
0	30.00	-40.00	6.000	2.40	6.000	-2.50
1	27.50	-48.67	1.37	1.35	1.375	-1.02
2	26.48	-49.43	0.18	1.01	0.178	
3						